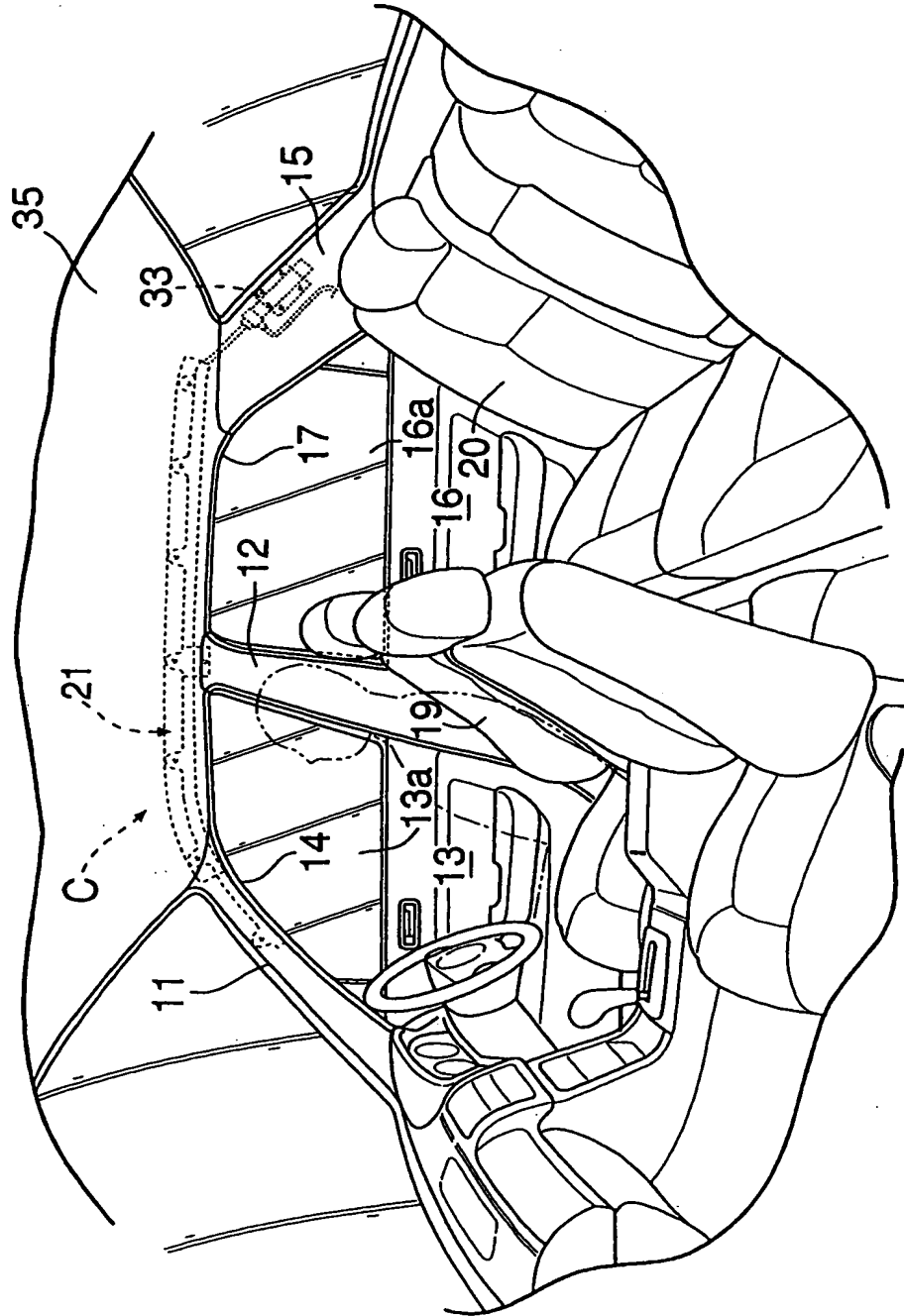
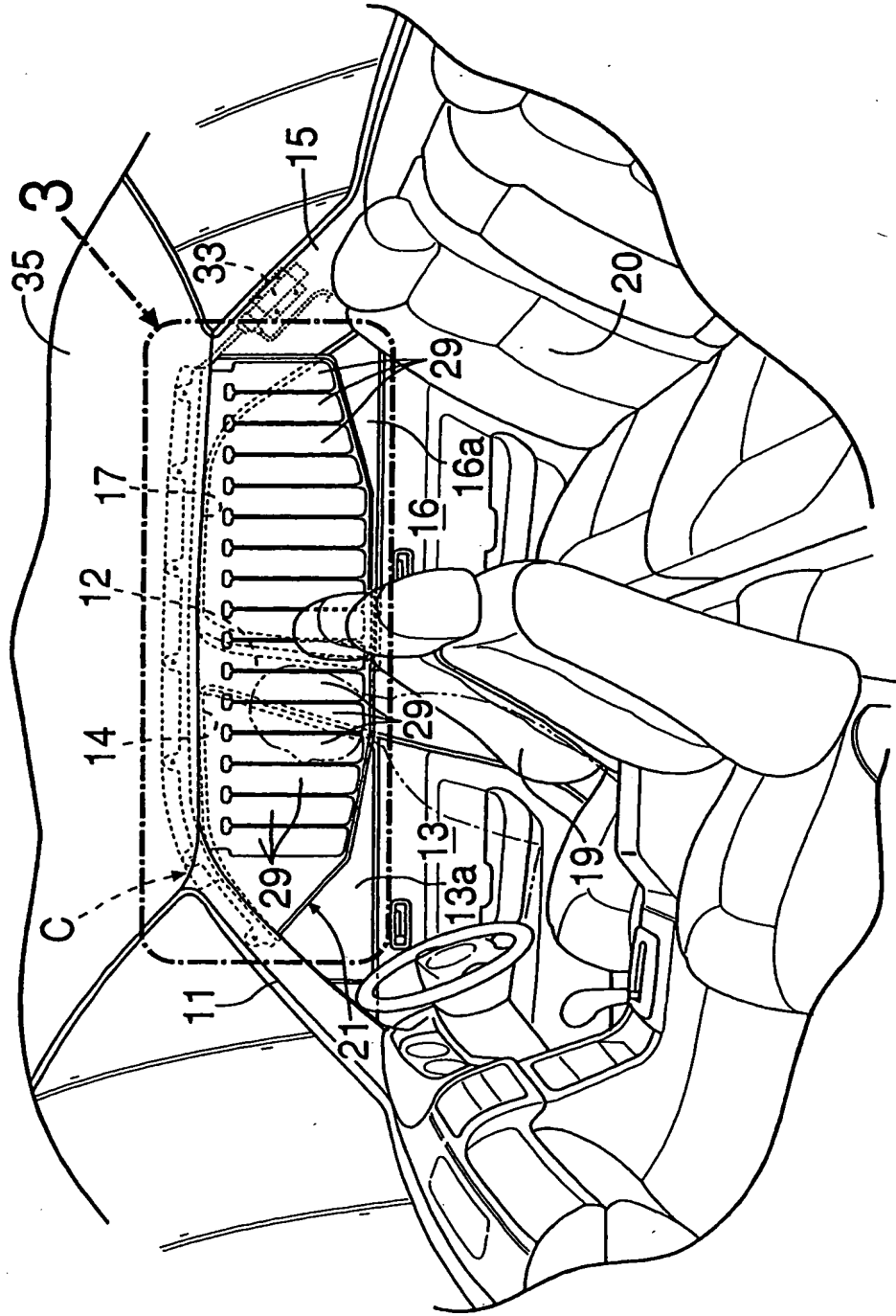


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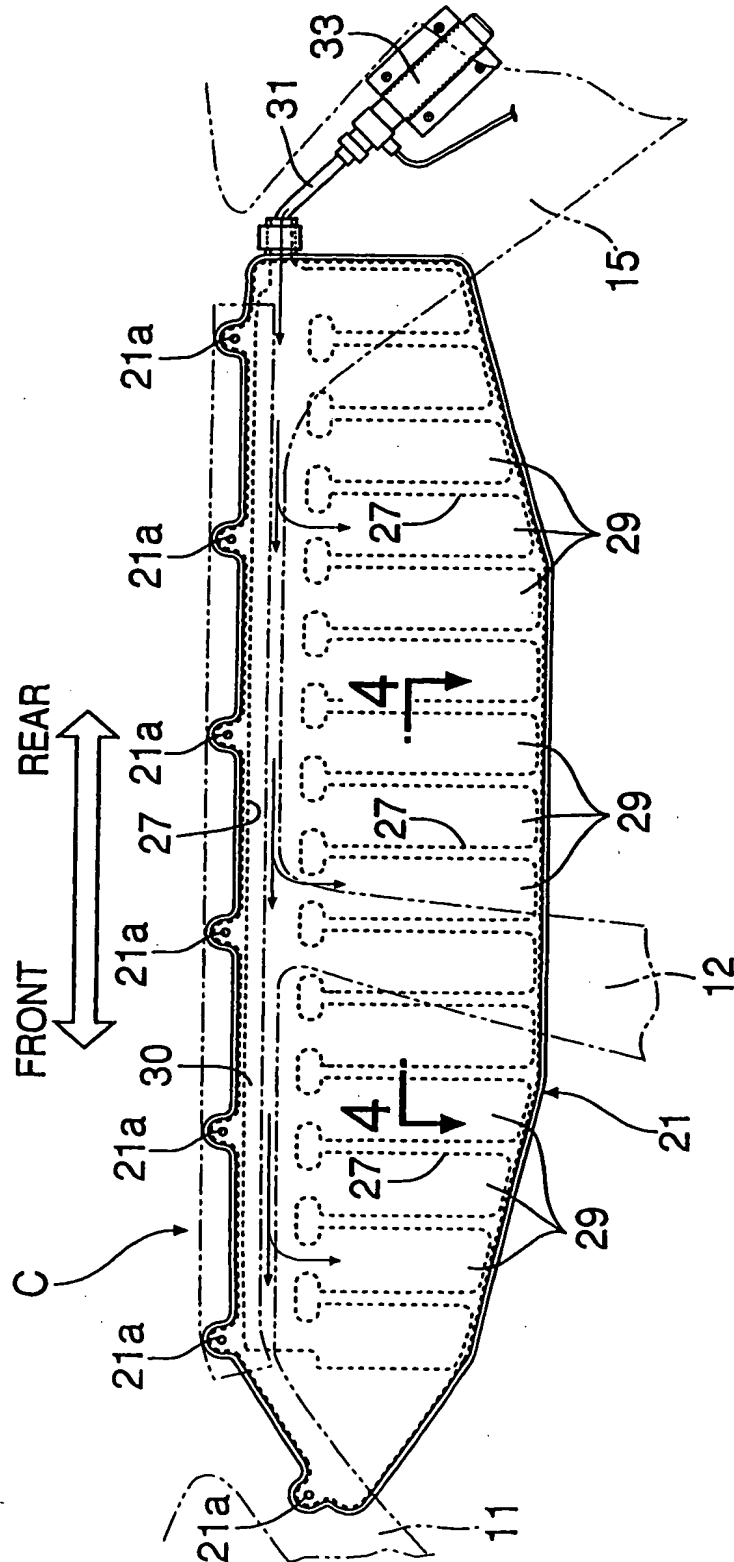
FIG. 1



**FIG. 2**

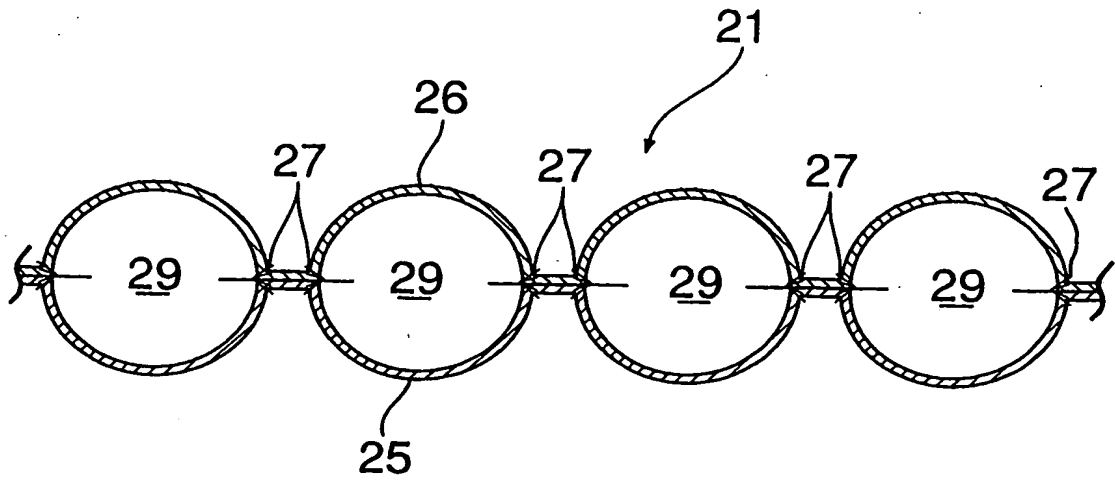


**FIG. 3**



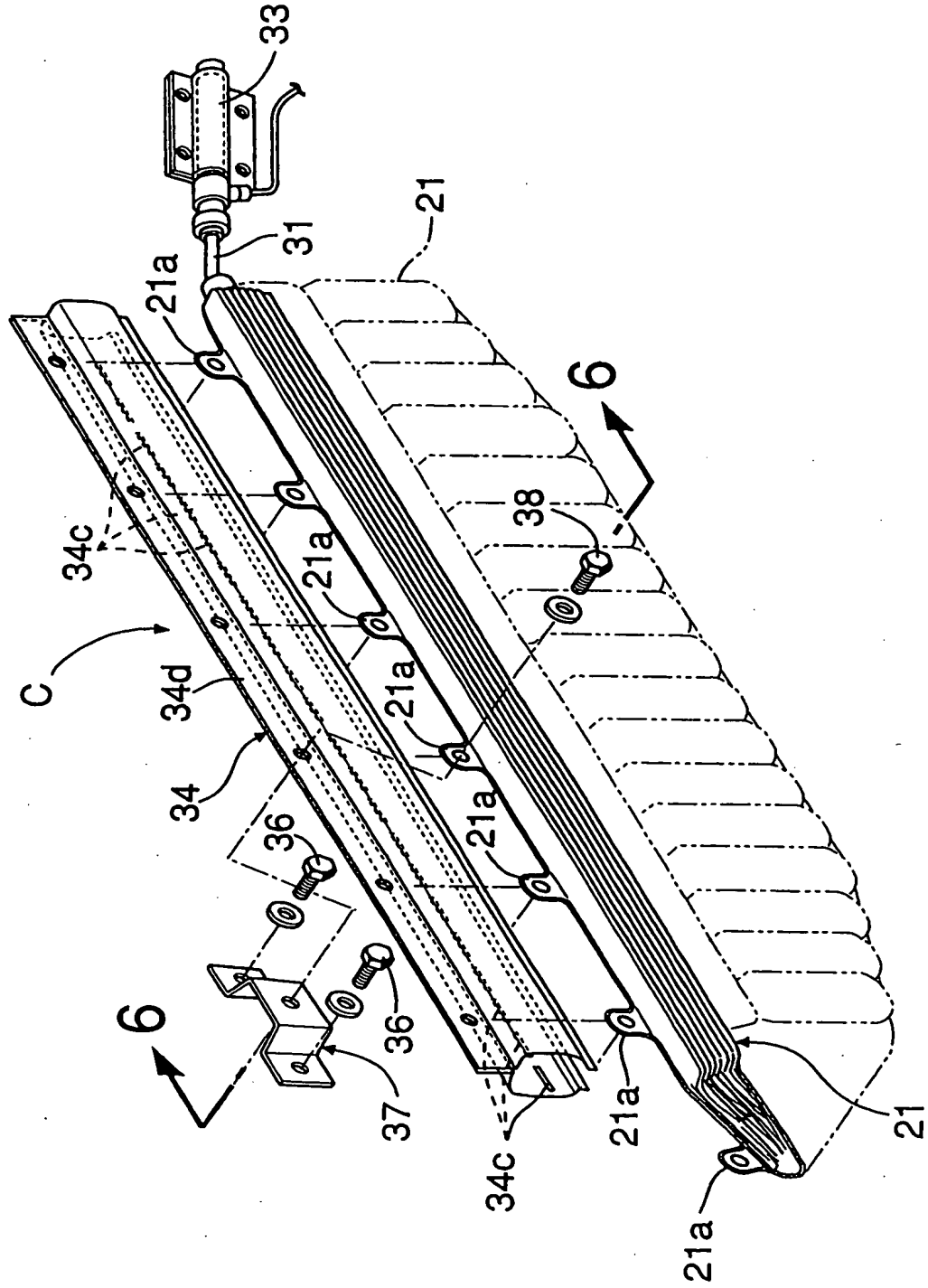
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FIG. 4



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FIG. 5



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FIG. 6

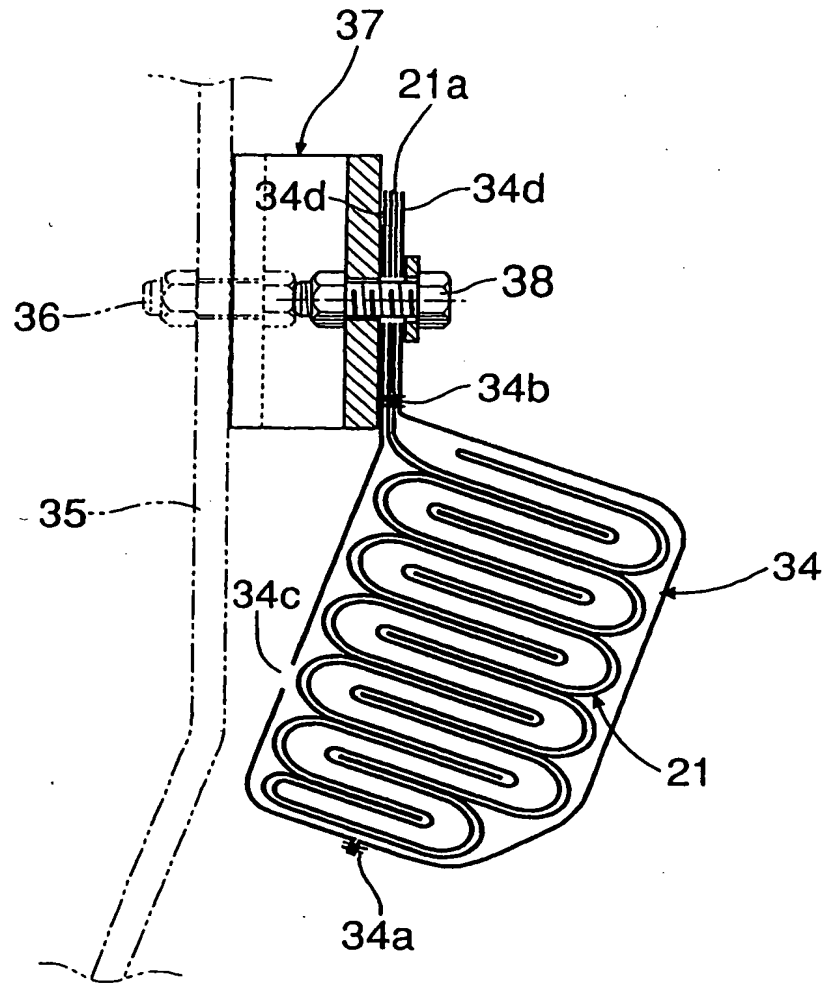
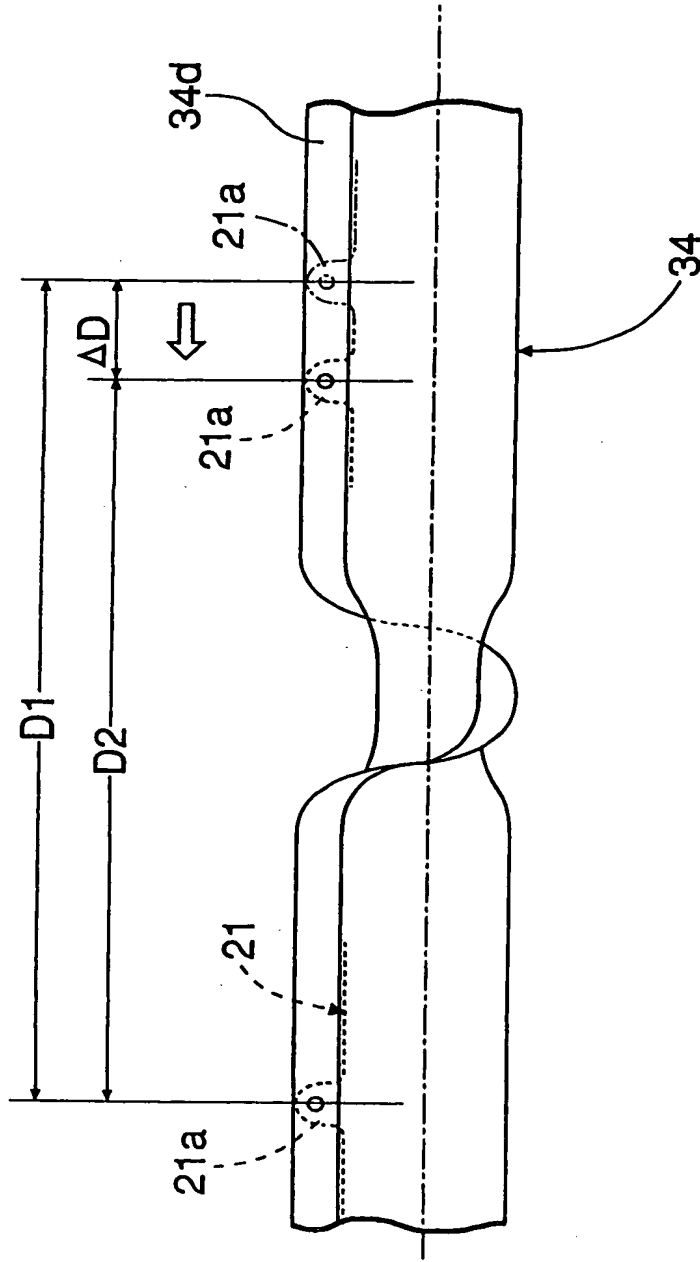


FIG. 7



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FIG. 8A

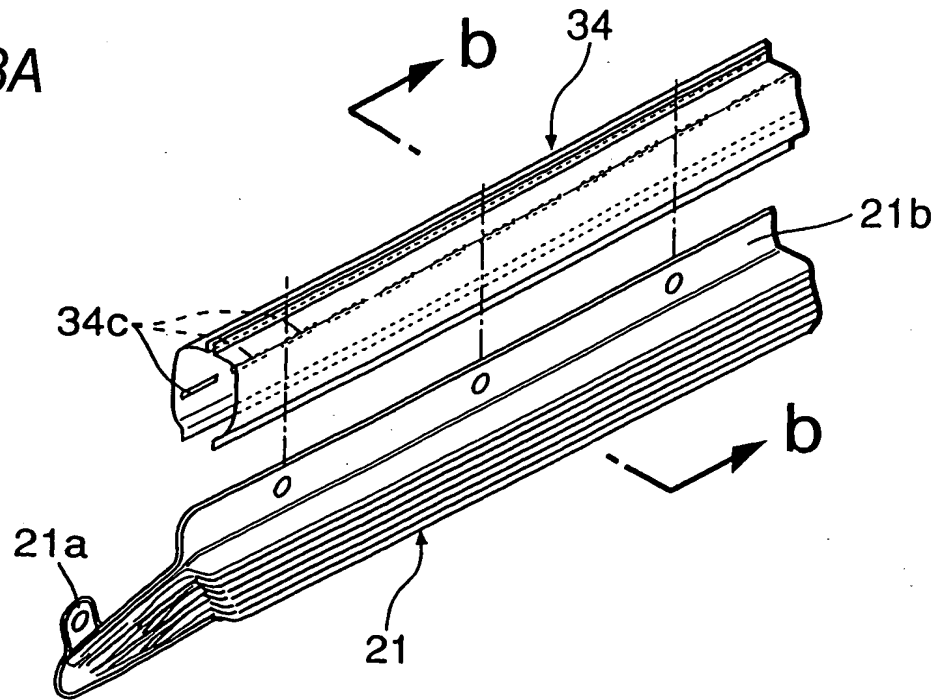
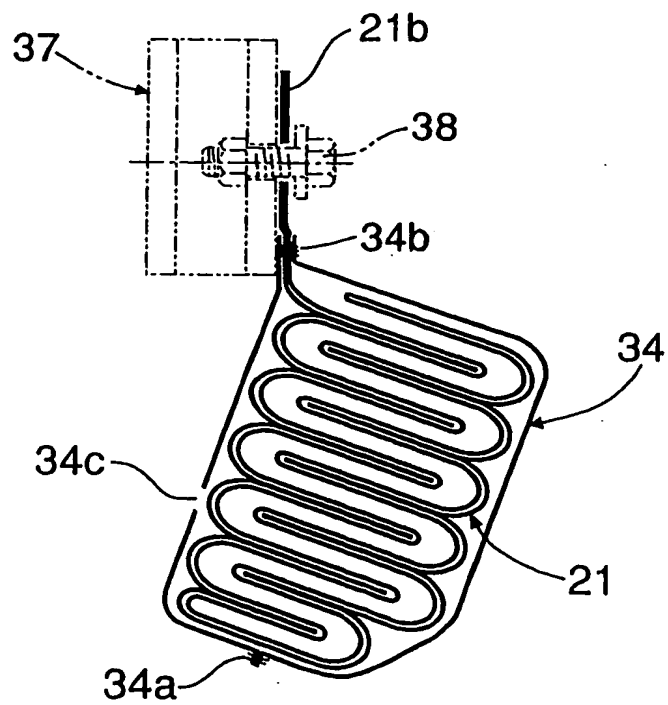


FIG. 8B





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FIG. 9A

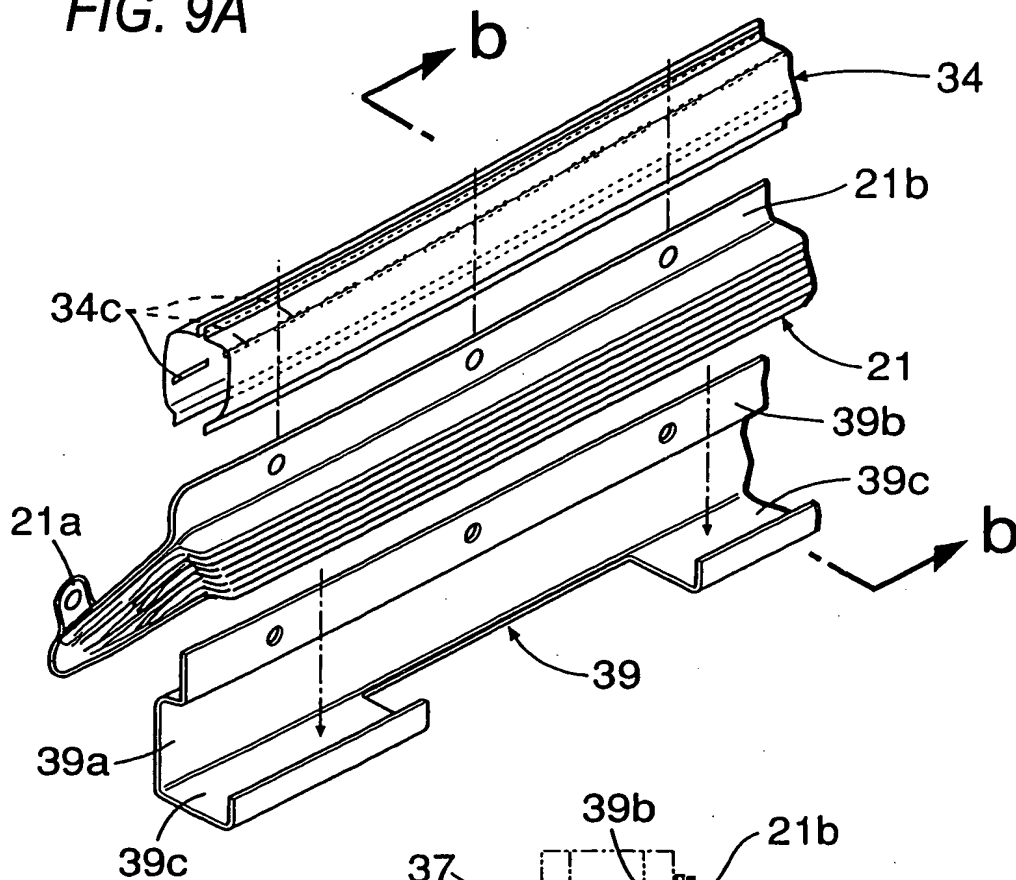
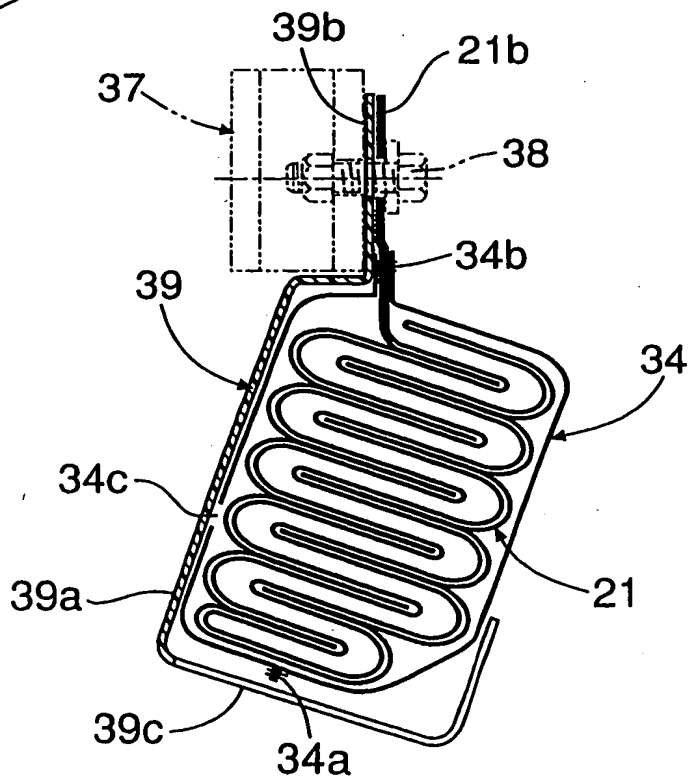


FIG. 9B

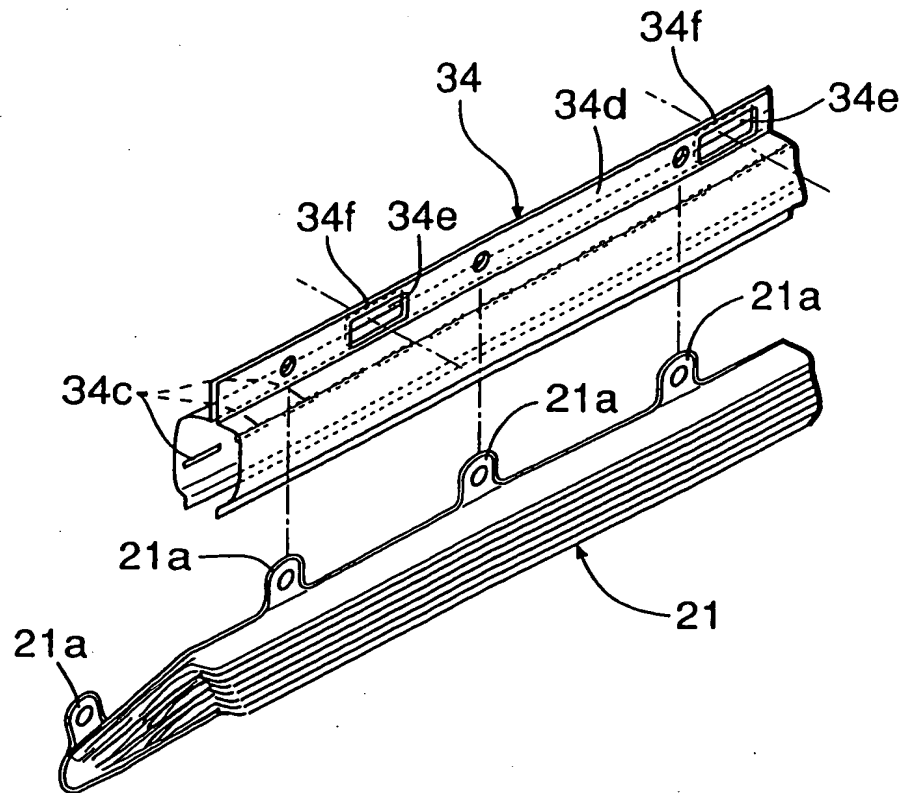


**FIG. 10A**

FIG. 10A is a perspective view of a second embodiment of the device. It shows a main body 21 with a series of longitudinal ribs. A component 34 is mounted on top of the body. Component 34 has a top surface 34c and a side surface 34d. The body 21 has several small circular features labeled 21a. A dashed arrow labeled 'b' indicates a direction of movement or force.

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FIG. 11



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FIG. 12A

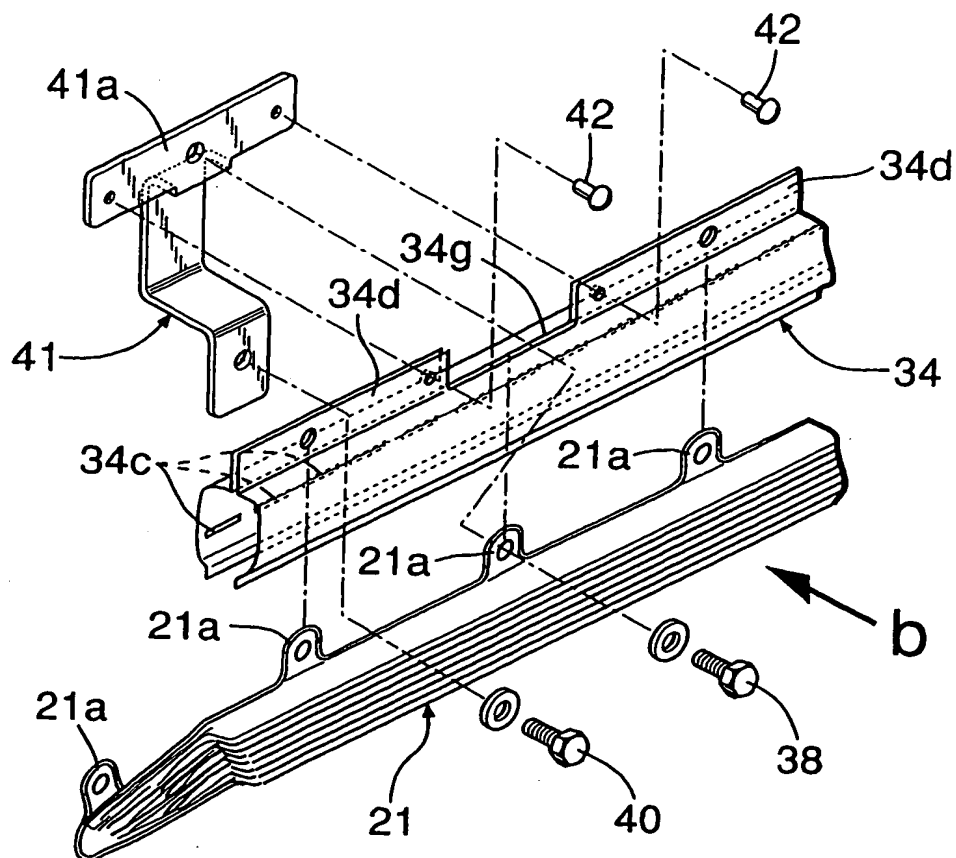
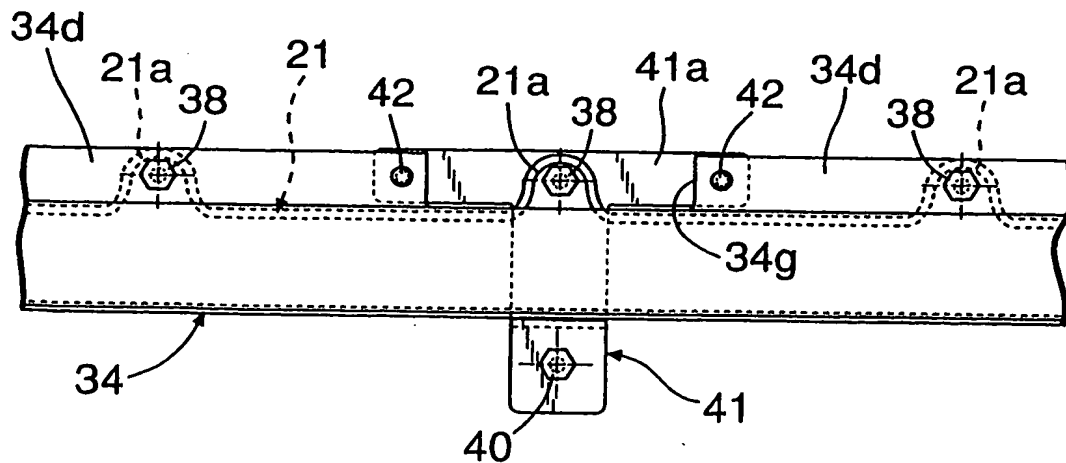


FIG. 12B



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FIG. 13A

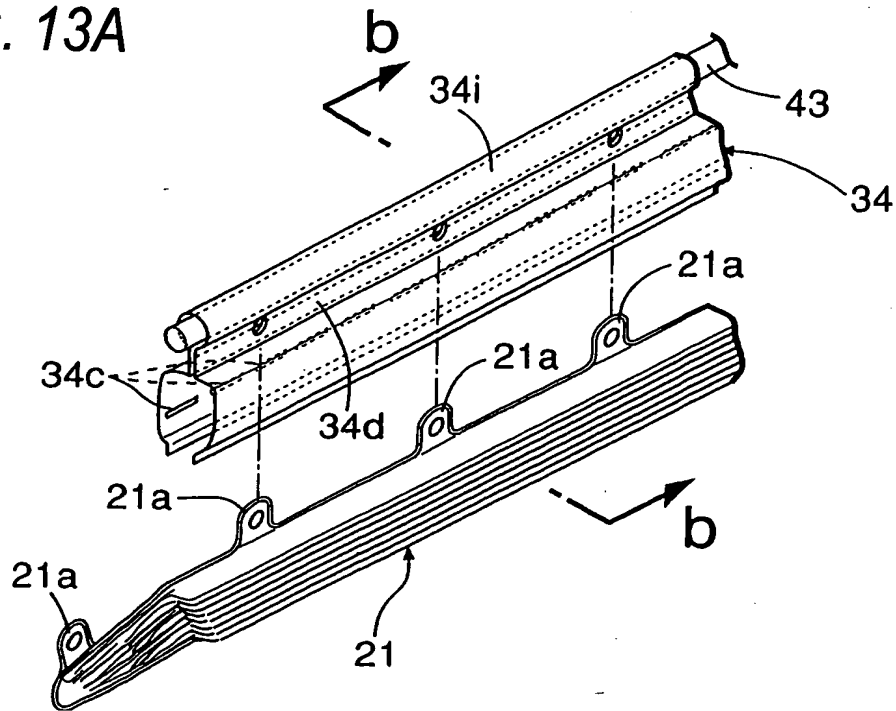


FIG. 13C

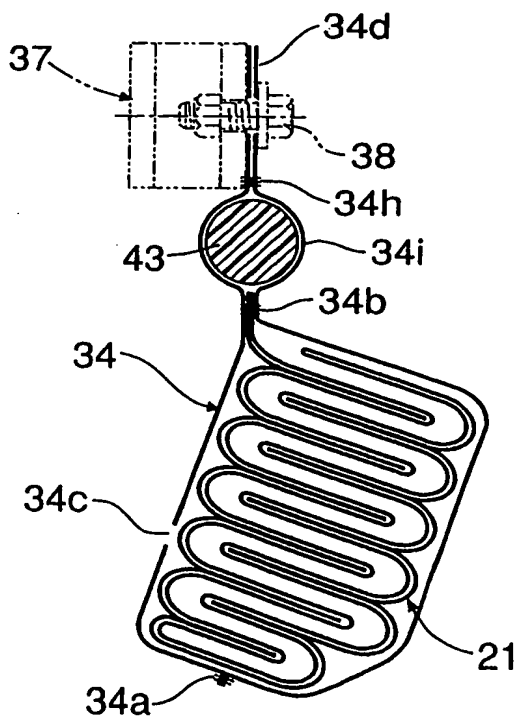
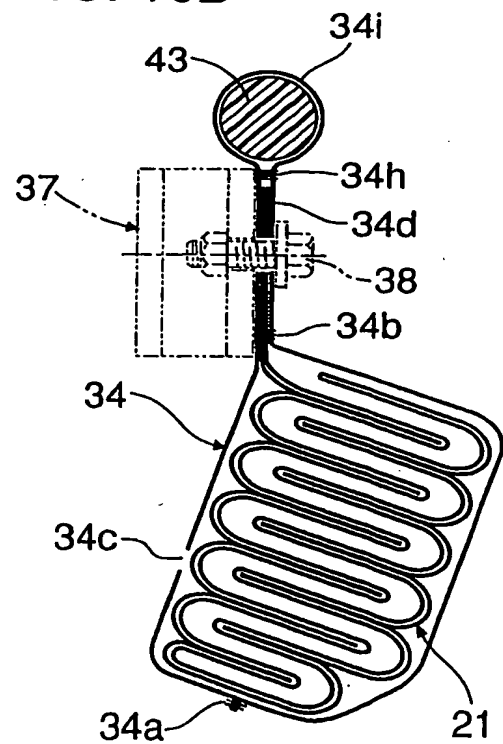


FIG. 13B





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FIG. 15A

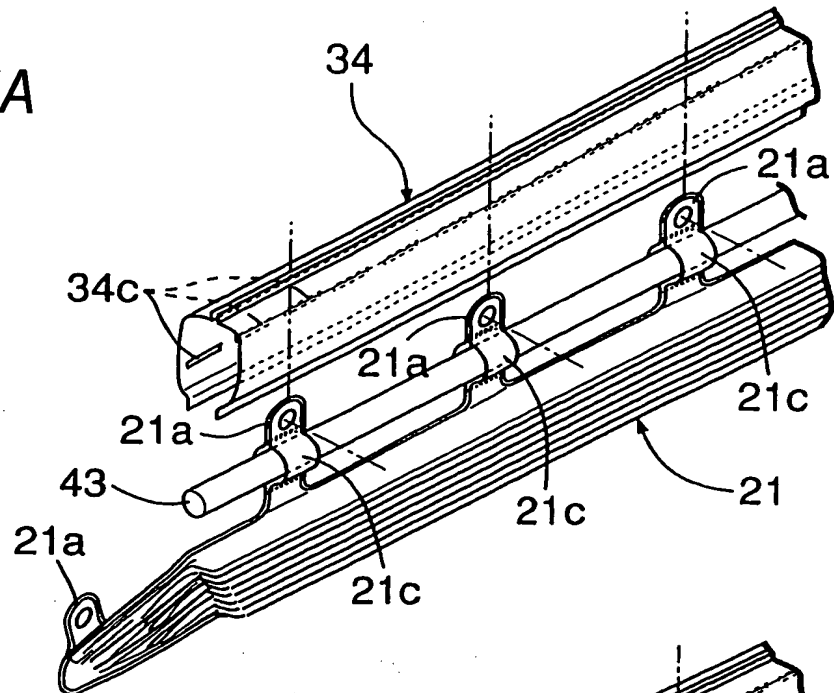
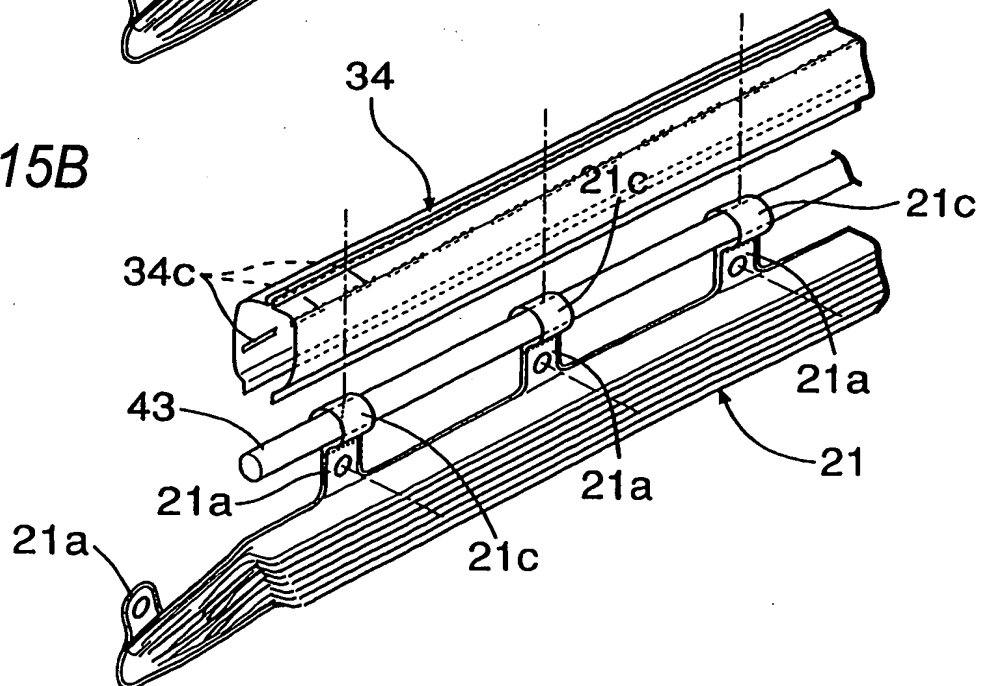
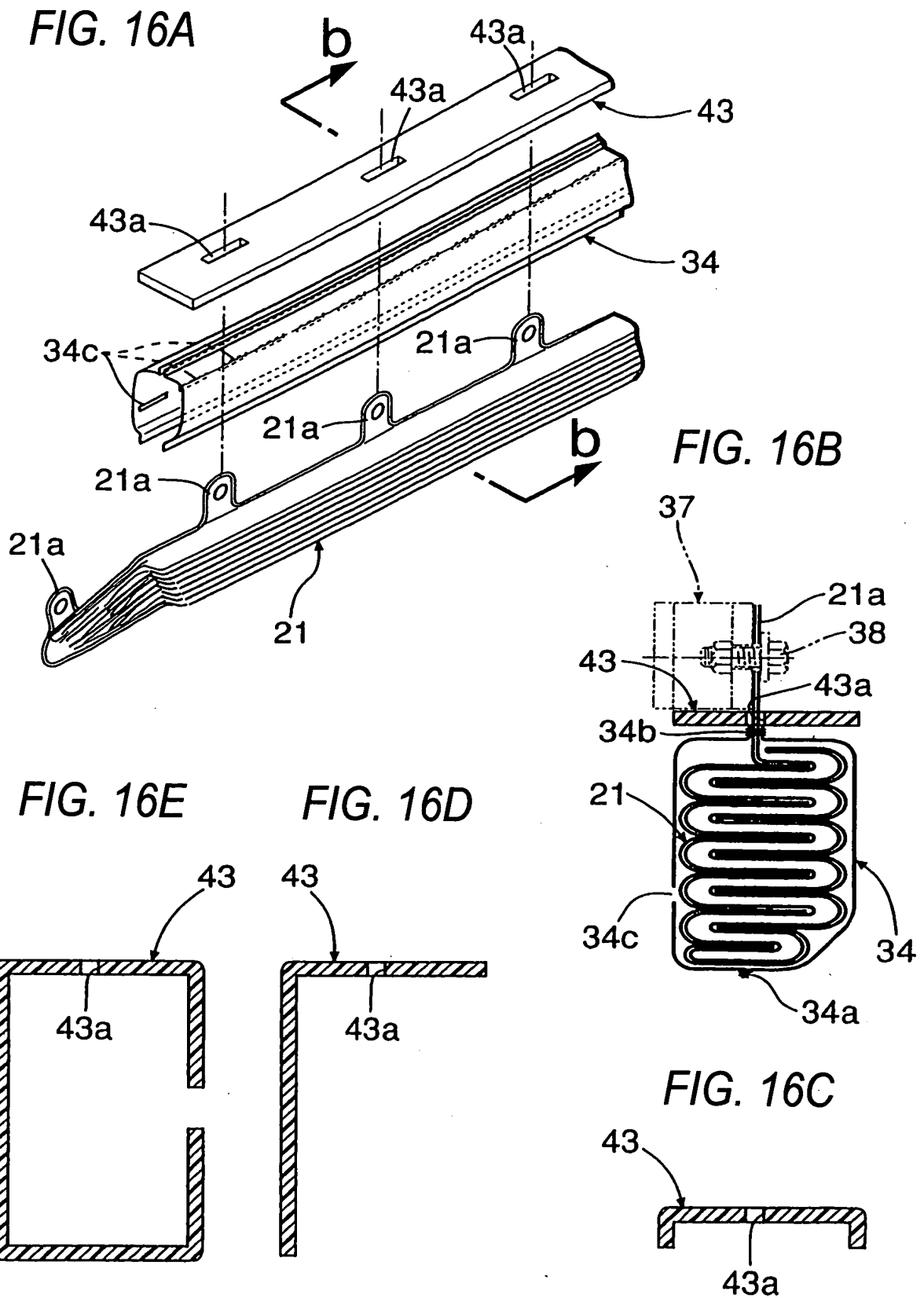


FIG. 15B



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FIG. 17A

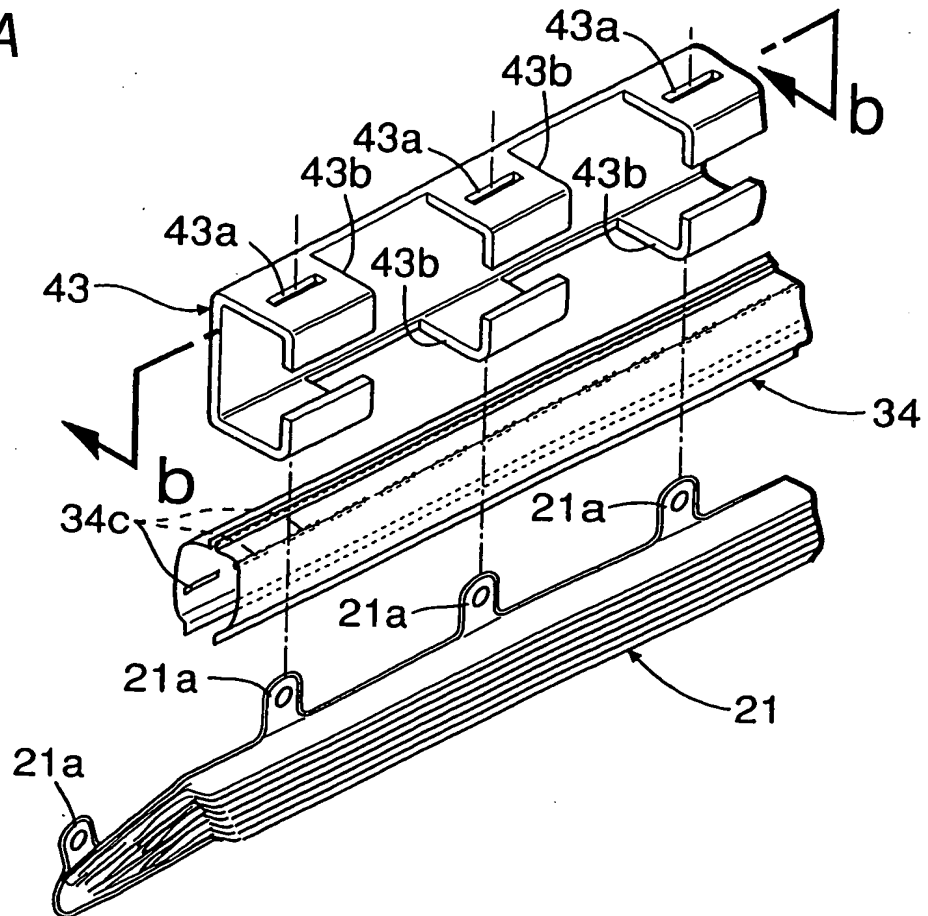


FIG. 17B

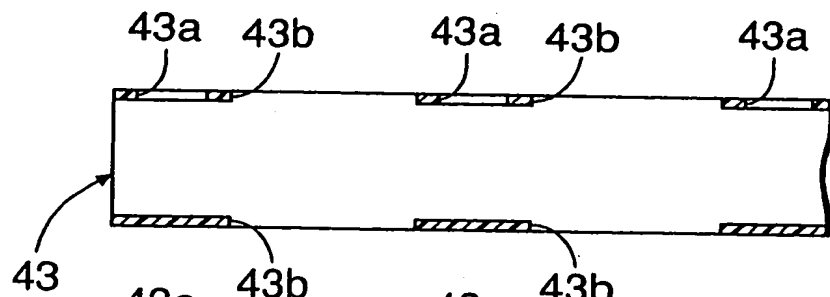
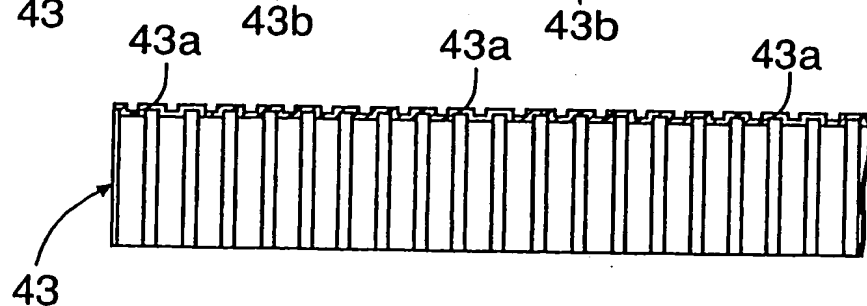
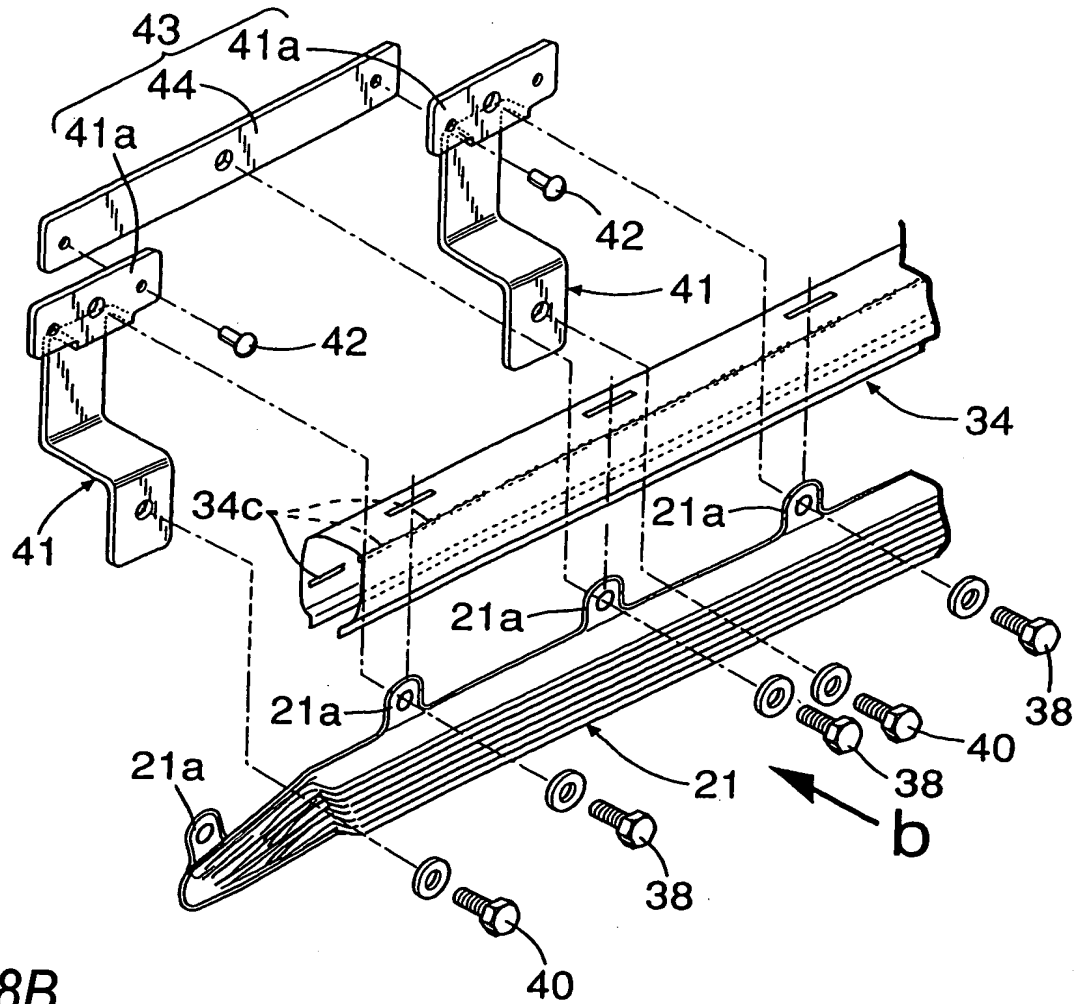


FIG. 17C



**FIG. 18A**



**FIG. 18B**

